Spacecraft Dynamics and Control

Matthew M. Peet Arizona State University

Lecture 11: Intro to Rocketry

Introduction

In this Lecture, you will learn:

Introduction to Rocketry

- Mass Consumption
- Specific Impulse and Rocket Types
- Δv limitations
- Staging

Numerical Problem: Suppose our mission requires a dry weight of 30kg. How much propellant is required to achieve a circular orbit of altitude 200km?

M. Peet

Questions about Propulsion

We have talked a bit about Δv .

- How is Δv created?
- How expensive is it?
- Is it really instantaneous?

Δv budget

A Typical mission uses a lot of Δv .

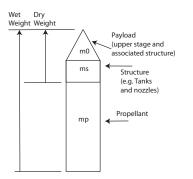
- How much propellant will we need?
- What is the maximum Δv budget?

| Propulsion Function | Typical Requirement |
|---|---|
| Orbit transfer to GEO (orbit insertion) | |
| Perigee burn | 2,400 m/s |
| Apogee burn | 1,500 (low inclination) to 1,800 m/s (high inclination) |
| Initial spinup | 1 to 60 rpm |
| LEO to higher orbit raising ∆V | 60 to 1,500 m/s |
| • Drag-makeup ΔV | 60 to 500 m/s |
| Controlled-reentry ΔV | 120 to 150 m/s |
| Acceleration to escape velocity from LEO parking orbit | 3,600 to 4,000 m/s into planetary trajectory |
| On-orbit operations (orbit maintenance) | |
| Despin | 60 to 0 rpm |
| Spin control | ±1 to ±5 rpm |
| Orbit correction ΔV | 15 to 75 m/s per year |
| East-West stationkeeping ΔV | 3 to 6 m/s per year |
| North-South stationkeeping ΔV | 45 to 55 m/s per year |
| Survivability or evasive maneuvers (highly variable) ΔV | 150 to 4,600 m/s |
| Attitude control | 3-10% of total propellant mass |
| Acquisition of Sun, Earth, Star | Low total impulse, typically <5,000 N*s, 1 K to 10 K pulses, 0.01 to 5.0 sec pulse width |
| On-orbit normal mode control with 3-axis stabilization, limit cycle | 100 K to 200 K pulses, minimum impulse bit of 0.01 N*s, 0.01 to 0.25 sec pulse width |
| Precession control (spinners only) | Low total impulse, typically <7,000 N*s, 1 K to 10 K pulses, 0.02 to 0.20 sec pulse width |
| Momentum management (wheel unloading) | 5 to 10 pulse trains every few days, 0.02 to 0.10 sec pulse width |
| 3-axis control during ΔV | On/off pulsing, 10 K to 100 K pulses, 0.05 to 0.20 sec pulse width |

Some Definitions

In a staged Launch system, the mass varies with time.

- Dry weight is the weight without propellant.
 - ► This is the final weight.
 - Craft plus payload
- There are several variations of dry weight.



| Weight Parameters | Comments |
|---|--|
| Spacecraft Dry Weight | Weight of all spacecraft subsystems and sensors, including weight growth allowance of 15-25% at concept definition |
| plus Propellant Yields | Weight of propellant required by the spacecraft to perform its mission when injected into its mission orbit |
| 2. Loaded Spacecraft Weight | Mission-capable spacecraft weight (wet weight) |
| plus Upper Stage Vehicle Weight Yields | Weight of any apogee or perigee kick motors and stages added to the launch system |
| 3. Injected Weight | Total weight achieving orbit |
| plus Booster Adapter Weight Yields | May also include airborne support equipment on the Space Shuttle |
| 4. Boosted Weight | Total weight that must be lifted by the launch vehicle |
| plus Performance Margin Yields | The amount of performance retained in reserve (for the booster) to allow for all other uncertainties. |
| 5. Payload Performance Capability | This is the payload weight contractors say their launch systems can lift |

5 / 31

Lecture 11 -Spacecraft Dynamics

-Some Definitions

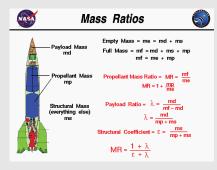


Some Definitions

. There are several variations of dry weight







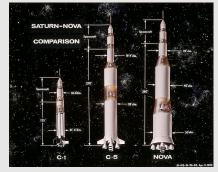


figure from NASA

How to create Thrust: Newton's Second Law

Approximation: Consider the expulsion of a piece of propellant, Δm .

Initial State:

- Propellant and Rocket move together.
- Total Momentum:

$$h_i = (m_r + \Delta m)v$$

before

Final State:

- Propellant and Rocket move separately.
- Rocket has velocity $v + \Delta v$
- Propellant has velocity v-c.
 - c is the exhaust velocity
- Total Momentum:

$$h_f = m_r(v + \Delta v) + \Delta m(v - c)$$



Conservation of Momentum:

• Setting $h_i = h_f$, we obtain:

$$(m_r + \Delta m)v = m_r(v + \Delta v) + \Delta m(v - c)$$

• Solving for Δv , we obtain

$$\Delta v = \frac{\Delta m}{m_r} c$$

M. Peet

-How to create Thrust: Newton's Second Law

How to create Thusix Newton's Second Law Againstantic Consider the explaint of a pixel of promising. An initial States.

The Against Again Consider the explaint A is a second of the explaint A in the explaint A is a second of the explaint A is a

- ullet In this slide, h_i is the initial linear momentum of rocket and propellant mass
- ullet v is the initial velocity of the spacecraft
- ullet m_r is the mass of the rocket
- Δm is the mass of the propellant.
- h_f is the final linear momentum of the rocket combined with the propellant. By conservation of momentum, $h_i=h_f$
- ullet Δv is the change in velocity of the rocket.
- Note: This is for a single particle of propellant Δm and can not be used to calculate Δv directly. We will integrate this equation of many particles of propellant to get the true Δv .

Continuous Thrust: The Rocket Equation

For a single particle of propellant, we have

$$\Delta v = \frac{\Delta m}{m_r} c$$

Dividing by Δt and taking the limit as $\Delta t \to 0$, we get

$$\dot{v}(t) = \frac{\dot{m}_r(t)}{m_r(t)}c$$

where we often assume constant mass flow rate $\dot{m}_r(t)$.



Returning to the differential form, we can directly integrate $dv = \frac{^C}{m_r} dm_r$

$$dv = \frac{c}{m_r} dm_r$$

to obtain the Rocket Equation:

$$\Delta v = v(t_f) - v(t_0) = c \ln \left[\frac{m(t_0)}{m(t_f)} \right]$$

Which is quite different from the approximation $\Delta v = \frac{\Delta m}{m} c!$

M. Peet 7 / 31 Lecture 11: Spacecraft Dynamics

-Continuous Thrust: The Rocket Equation

- $\dot{m}_r = \lim_{\Delta t \to 0} \frac{\Delta m}{\Delta t}$ is the rate at which we are using up propellant. Note this doesn't affect $\Delta v!$
- Although liquid and hybrid rockets can control this rate, in practice, we want to make it as large as possible so that the Δv happens quickly.
- $m(t_0)$ is the mass before the burn. $m(t_f)$ is the mass after the burn.
- ullet $v(t_f)$ is the velocity after the burn. $v(t_0)$ is the velocity before the burn.

Sizing the Propellant: Inverse Rocket Equation

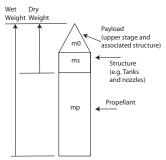
Now we have an expression for Δv as a function of wet and dry weights.

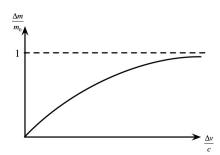
$$\Delta v = v(t_f) - v(t_0) = c \ln \left[\frac{m(t_0)}{m(t_f)} \right]$$

where recall $m_0 = m(t_0)$ is the mass before thrust and $m(t_f)$ is the mass after.

- Δv is a function of the ratio of wet weight to dry weight
- For a given maneuver, we can calculate the required propellant

$$\frac{\Delta m}{m_0} = 1 - e^{-\frac{\Delta v}{c}}$$





M. Peet

Sizing the Propellant: Inverse Rocket Equation

Sing the Propellant: Inverse Rodet Equation

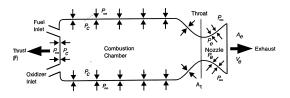
Now us how an expression for Δu as function and end symples. We are u(x) = (u(x) - u(x)) = 4u. In this case of u(x) = (u(x) - u(x)) = 4u. In this manual wife when and u(x) is the same of u(x) = u(x) = 4u. For u(x) = u(x) = u(x) = 4u. For u(x) = u(x) = u(x) = u(x) = u(x). The u(x) = u(x) = u(x) = u(x) is the same of u(x) = u(x) = u(x) = u(x) = u(x). The u(x) = u(x) = u(x) = u(x) = u(x) is the same of u(x) = u(x) = u(x) = u(x) = u(x). The u(x) = u(x) = u(x) = u(x) is the same of u(x) = u(x) = u(x) = u(x).

- $m(t_0)$ is the wet weight (with propellant).
- $m(t_f)$ is the dry weight (after all propellant has been used up)
- First equation is called the rocket equation (May 10, 1897), derived by Konstantin E. Tsiolkovsky (1857-1935). Recluse who lived in a log cabin outside Moscow. First person to conceive of space elevator (inspired by Eiffel tower).
- Assuming no structural mass, to launch a 2000 kg rocket to Alpha Centaur would require a rocket of more than 10,000,000 kg (weight of Eiffel Tower) and take 142,000 years to arrive.

Effective Exhaust Velocity

The efficiency of the rocket depends on the relative velocity of the propellant, c.

• However, there is also a force due to pressure, $F = A_e(P_e - P_{\infty})$.



The *effective* velocity, c, of propellant is determined by configuration of the rocket:

$$c = V_e + \frac{A_e}{\dot{m}} [P_e - P_\infty]$$

Note: P_e gives a boost to thrust, but at the cost of a lower V_e

- ullet As V_e increases, P_e drops (particles accelerate out of high-P regions)
- It is always best to maximize V_e (we want $P_e = P_{\infty}$).
- In space, this implies we want $\frac{A_e}{A_t}$ as large as possible.
- ullet Propellant is usually rated by c and not $V_e!$

M. Peet

Effective Exhaust Velocity

The efficiency of the rocket depends on the relative velocity of the propellant, c.

* However, there is also a force after pressure, $F = A_{c}(P_{c} - P_{m})$.

The effective velocity, c_i of propellant is determined by coeffiguration of the rocket: $c = V_c + \frac{A_c}{10}[P_c - P_\infty]$

Note: P_c gives a boost to threat, but at the cost of a lower V_c • As V_c increases, P_c deeps (particles accelerate out of high-P regions) • It is always best to maximize V_c (see word: $P_c = P_{cc}$). • In space, this implies we ware: $\frac{A_c}{2}$ as large as possible. • Propellast is unasily rated by c and not V_c !

- In previous slides, we have been using c instead of V_e for exhaust velocity so as not to confuse you later. However, these formulae should be used with *effective* exhaust velocity, c.
- P_{∞} is the atmospheric pressure.
- ullet P_e is the pressure at exit from the nozzle.
- A_t is the area of the throat.
- A_e is the area of the nozzle exit.
- The effective exhaust velocity of H_2 - O_2 propellant in space is 4,440 m/s
- On the ground, there is an optimal A_e corresponding to $P_e = P_{\infty}$.
- ullet Expansion ratio (A_e/A_t) of 117:1 for Merlin 1D Falcon Heavy upper stage.

Pressure Changes affect Efficiency on Saturn V

Specific Impulse

Definition 1.

The **Specific Impulse** is the ratio of the momentum imparted to the weight (on earth) of the propellant.

$$I_{sp} = \frac{\Delta mc}{\Delta mg} = \frac{c}{g}$$

Since $\Delta v = c \ln \left[\frac{m_0}{m_f} \right]$, specific impulse gives a measure of how efficient the propellant is.

| | Orbit Insertion | | Orbit Insertion | | Orbit Insertion Orbit Maintenance | | Attitude | Typical Steady State I _{sp} |
|--------------------------|-----------------|------------|-----------------|---------|-----------------------------------|--|----------|---|
| Propulsion Technology | Perigee | Apogee | and Maneuvering | Control | (s) | | | |
| Cold Gas | | | ~ | ~ | 30–70 | | | |
| Solid | - | - | | | 280-300 | | | |
| Liquid | | | / | | | | | |
| Monopropellant | | | | ~ | 220-240 | | | |
| Bipropellant | 1 | · | · | ~ | 305-310 | | | |
| Dual mode | 1 | · | · · | V | 313-322 | | | |
| Hybrid | - | <u>ر</u> ا | · • | | 250-340 | | | |
| Electric | | 1 | | | 300-3,000 | | | |

- measured in seconds, I_{sp} tells, for any amount of propellant mass, how many seconds the rocket will provide thrust equal to the weight (q=9.81) of the propellant consumed.
- \bullet Because the effective velocity depends on atmospheric pressure, I_{sp} is different on the surface of the earth vs. in space.
- ullet Typically, I_{sp} assumes a perfectly expanded rocket.
- Isp for Starship is 320 (atmo) to 360 (space) for Oxygen-Methane

Example

Problem: Suppose our mission requires a dry weight of $m_L=30{\rm kg}$. Using an I_{sp} of 300s, how much propellant is required to achieve a circular orbit of altitude 200km?

Solution: A Circular orbit at 200km requires a total velocity of

$$v = \sqrt{\frac{\mu}{r}} = \sqrt{\frac{398600}{6578}} = 7.78 km/s$$

Add 1.72km/s to account for gravity and drag. This totals 9.5km/s=9500m/s. The $I_{sp}=300s$, which means c=3000m/s. Thus we have

$$\frac{m_p}{m_0} = 1 - e^{-\frac{\Delta v}{c}} = .9579$$

Since
$$m_0 = m_L + m_p$$
, $m_p = m_L \left(\frac{.9579}{1 - .9579} \right) = 682 \text{kg}$.

- Which is sort of a lot!
- What about structural mass and Δv for orbital maneuvers?
- We'll return to this problem later

M. Peet Lecture 11: Spacecraft Dynamics 12 / 31

Since v

• m_0 is wet mass, dry mass plus propellant.

• $\Delta m = m_p$

2025-04-01

Example

Problem: Suppose our mission requires a dry unight of $m_L = 30kg$. Using an I_{sp} of 300k, how much propellant is required to achieve a circular orbit of altitude 2000km? Solution: A Groular orbit at 2000km requires a total velocity of

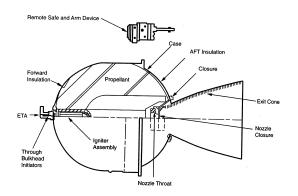
Add 1.72km/s to account for gravity and drag. This totals 9.5km/s=9500m/s. The $I_{sp}=300s$, which means c=3000m/s. Thus we

 $\frac{m_p}{m_0} = 1 - e^{-\frac{\Delta x}{\lambda}} = .9579$

Since $m_0=m_L+m_p,\ m_p=m_L\left(\frac{8070}{1-8000}\right)=682 {\rm kg}.$ • Which is sort of a lot!

• What about structural mass and Δv for orbital maneuvers? • We'll return to this problem later

Solid Rocket Motors



Advantages:

- Simple
- Reliable
- Low Cost

Disadvantages:

- Limited Performance
- Not Adjustable (Safety)
- Toxic Byproducts

Solid Rocket Motors

| Motor | Total Impulse (N·s) | Loaded Weight (kg) | Pro- pellant Mass Fraction | Avg. Thrust (lb _f) | Avg. Thrust (N) | Max. Thrust (N) | Effec- tive I _{SP} (sec) | Status | |
|-------------------------|---------------------------|--------------------------|-------------------------------------|--------------------------------------|-----------------------|-----------------------|--|-------------|--|
| | | 10,374 | 0.94 | 44,610 | 198,435 | 260,488 | 295.5 | Flown | |
| IUS SRM-1 (ORBUS-21) | 2.81 × 10 ⁷ | | | 35,375 | 157.356 | 193,200 | 285.4 | Flown | |
| LEASAT PKM | 9.26×10^{6} | 3,658 | 0.91 | 35,375 | | , | | Flown | |
| STAR 48A | 6.78 × 10 ⁶ | 2,559 | 0.95 | 17,900 | 79,623 | 100,085 | 283.9 | | |
| STAR 48B(S) | 5.67 × 10 ⁶ | 2,135 | 0.95 | 14,845 | 66,034 | 70,504 | 286.2 | Qualified | |
| | 5.79 × 10 ⁶ | 2,141 | 0.95 | 15,160 | 67,435 | 72,017 | 292.2 | Qualified | |
| STAR 48B(L) | | 2,459 | | | | | 293.5 | In develop. | |
| STAR 62 | 7.12 × 10 ⁶ | 1 | | 44,608 | 198,426 | 242,846 | 288.0 | In develop. | |
| STAR 75 | 2.13×10^{7} | 8,066 | 0.93 | | | | | Flown | |
| IUS SRM-2 | 8.11 × 10 ⁶ | 2,995 | 0.91 | 18,020 | 80,157 | 111,072 | 303.8 | | |
| (ORBUS-6) | 1.16 × 10 ⁵ | 47 | 0.88 | 1,577 | 7,015 | 9,608 | 285.7 | Flown | |
| STAR 13B | 1 | | 0.94 | 5,960 | 26,511 | 32,027 | 292.0 | Flown | |
| STAR 30BP | 1.46 × 10 ⁶ | | | 1 | 1 | 37.031 | 284.6 | Flown | |
| STAR 30C | 1.65 × 10 ⁶ | 626 | 0.95 | 7,140 | 1 | | | Flown | |
| STAR 30E | 1.78 × 10 ⁶ | 667 | 0.94 | 7,910 | 1 | 1 . | 1 | 1 | |
| STAR 37F | 3.02 × 10 ⁶ | 1,149 | 0.94 | 9,911 | 44,086 | 49,153 | 291.0 | Flown | |

Figure: Thiokol (ATK Launch Systems) = STAR, LEASAT; United Technologies = IUS

M. Peet Lecture 11: Spacecraft Dynamics 14 / 31

Liquid Monopropellants

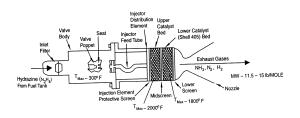


Figure: Typical Hydrazine Monopropellant

Advantages:

- Simple
- Reliable
- Low Cost

Disadvantages:

 Lower Performance than bipropellant

Liquid Bipropellants



Figure: Raptor Engine

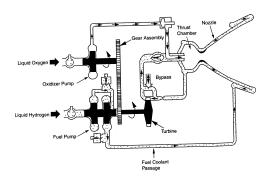


Figure: Centaur O_2 - H_2 upper stage.

Advantages:

- High Performance
- Adjustable

Disadvantages:

- Complicated
- Dangerous
- Sometimes Toxic

Liquid Bipropellants

| Туре | Propellant | Energy | Vacuum I _{sp} (sec) | Thrust Range (N) | Thrust Range (lb _f) | Avg Bulk Density (g/cm³) |
|-------------------------|--|----------------------------------|------------------------------------|----------------------------|---------------------------------------|--------------------------------|
| Cold Gas | N ₂ , NH ₃ , Freon, helium | High pressure | 50-75 | 0.05-200 | 0.01-50 | 0.28°, 0.60, 0.96° |
| Solid Motor | t | Chemical | 280-300 | 50-5 × 10 ⁶ | 10-106 | 1.80 |
| Liquid: | | | | | | |
| Monopropellant | H ₂ O ₂ , N ₂ H ₄ | Exothermic decom- position | 150-225 | 0.05-0.5 | 0.01-0.1 | 1.44, 1.0 |
| Bipropellant | O ₂ and RP-1 | Chemical | 350 | 5-5 × 10 ⁶ | 1-106 | 1.14 and 0.80 |
| | O ₂ and H ₂ | Chemical | 450 | 5-5×10 ⁶ | 1-106 | 1.14 and 0.07 |
| | N ₂ O ₄ and MMH (N ₂ H ₄ , UDMH) | Chemical | 300-340 | 5-5×10 ⁶ | 1-106 | 1.43 and 0.86 (1.0, 0.79) |
| | F ₂ and N ₂ H ₄ | Chemical | 425 | 5-5 × 10 ⁶ | 1-106 | 1.5 and 1.0 |
| | OF ₂ and B ₂ H ₆ | Chemical | 430 | 5-5 × 10 ⁶ | 1-106 | 1.5 and 0.44 |
| | CIF ₅ and N ₂ H ₄ | Chemical | 350 | 5-5 × 10 ⁶ | 1-106 | 1.9 and 1.0 |
| Dual Mode | N ₂ O ₄ /N ₂ H ₄ | Chemical | 330 | 3-200 | - | 1.9 and 1.0 |
| Water Electrolysis | H ₂ 0→H ₂ + O ₂ | Electric / chemical | 340-380 | 50-500 | 10-100 | 1.0 |
| Hybrid | O ₂ and rubber | Chemical | 225 | 225-3.5 × 10 ⁵ | 50-75,000 | 1.14 and 1.5 |
| Electrothermal: | | | | | | |
| Resistojet | N ₂ , NH ₃ , N ₂ H ₄ , H ₂ | Resistive heating | 150-700 | 0.005-0.5 | 0.001-0.1 | 0.28*, 0.60, 1.0 0.019* |
| Arcjet | NH ₃ , N ₂ H ₄ , H ₂ | Electric arc heating | 450-1,500 | 0.05-5 | 0.01-1 | 0.60, 1.0, 0.019 |
| Electrostatic: | | | | | | |
| Ion | Hg/A/Xe/Cs | Electrostatic | 2,000- 6,000 | 5 × 10 ⁻⁶ -0.5 | 10-6-0.1 | 13.5/0.44*/2.73 /1.87 |
| Colloid | Glycerine | Electrostatic | 1,200 | 5 × 10 ⁻⁶ -0.05 | 10-6-0.01 | 1.26 |
| Hall Effect Thruster | Xenon | Electrostatic | 1,500- 2,500 | 5 × 10-6-0.1 | 10-6-0.02 | 0.22 |
| Electromagnetic: | | | | | | |
| MPD‡ | Argon | Magnetic | 2,000 | 25-200 | 5-50 | 0.44* |
| Pulsed Plasma | Teflon | Magnetic | 1,500 | 5×10-6-0.005 | 10-6-0.001 | 2.2 |
| Pulsed Inductive | Argon NoHa | Magnetic Magnetic | 4,000 2,500 | 2-200 2-200 | 0.5-50 0.5-50 | 0.44 1.0 |

Lecture 11 Spacecraft Dynamics

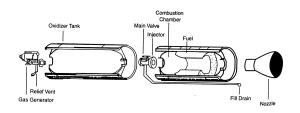
—Liquid Bipropellants

Impulse Densities of Several Propellants Pc = 1000 PSI to vacuum with 100:1 nozzle (sorted highest to lowest)

| | | | | | Oxidizer | Fuel | Avg | Density |
|-------------|------------------|----------|----------|--------|----------|---------|---------|---------------|
| | | | Pressure | Isp(v) | Density | Density | Density | Impulse |
| Oxidizer | Fuel | OF Ratio | (PSI) | (s) | lb/cuft | lb/cuft | lb/cuft | (lb-f-s/cuft) |
| AP | HTPB-AI | 5.17 | 1000 | 312.6 | 121.7 | 167.6 | 127.4 | 39810 |
| Nitric Acid | Furfuryl Alcohol | 2.40 | 1000 | 323.0 | 93.7 | 70.5 | 85.5 | 27600 |
| H2O2 (100%) | Kerosene | 7.00 | 1000 | 331.0 | 90.5 | 49.9 | 82.2 | 27195 |
| N2O4 | Hydrazine | 1.08 | 1000 | 348.0 | 90.1 | 63.7 | 75.2 | 26152 |
| Nitric Acid | Kerosene | 4.60 | 1000 | 310.0 | 93.7 | 49.9 | 81.0 | 25111 |
| H2O2 (90%) | Kerosene | 7.00 | 1000 | 310.0 | 86.6 | 49.9 | 79.3 | 24587 |
| AK27 | T185 | 3.56 | 1000 | 312.0 | 92.4 | 49.3 | 77.5 | 24191 |
| Lox | Kerosene | 2.33 | 1000 | 347.0 | 71.2 | 49.9 | 63.1 | 21899 |
| Lox | IPA | 1.70 | 1000 | 341.0 | 71.2 | 49.1 | 61.0 | 20810 |
| AP | HTPB | 2.33 | 1000 | 224.0 | 121.7 | 57.4 | 91.1 | 20399 |
| Lox | Butane | 2.20 | 1000 | 365.0 | 71.2 | 37.5 | 55.6 | 20290 |
| Lox | Methane | 2.77 | 1000 | 365.0 | 71.2 | 29.0 | 51.4 | 18759 |
| Lox | Propane | 2.20 | 1000 | 355.0 | 71.2 | 30.8 | 50.5 | 17939 |
| Lox | LH2 | 6.00 | 1000 | 457.0 | 71.2 | 4.4 | 22.6 | 10307 |

methalox is 322-365 Isp at average bulk density of .46. But less soot and doesn't freeze.

Hybrid Rockets



Advantages:

- Throttled
- Non-Explosive

Disadvantages:

- Requires Oxidizer
- Bulky

Flown on SpaceShipOne (Developed by SpaceDev, Oxidizer - N02, $I_{sp}=250s,\,\rm Max$ Thrust 74kN)

M. Peet

Lecture 11: Spacecraft Dynamics

Hybrid Rockets

| Motor | Average Thrust (lb _f) | Average Thrust (kN) | Burn Duration (sec) | Fuel | Oxidizer | Comments | | | | |
|-------------|---|---------------------------|---------------------------|------|----------|--|--|--|--|--|
| American Re | American Rocket Company | | | | | | | | | |
| H-500 | 75,000 | 333 | 70 | нтрв | LOx | Qualified for flight | | | | |
| H-250 | 32,000 | 142 | | нтрв | LOx | In development | | | | |
| H-50 | 10,000 | 44 | | нтрв | LOx | In development | | | | |
| U-50 | 6,500 | 29 | | нтрв | LOx | In development | | | | |
| U-1 | 100 | 0.44 | | НТРВ | LOx | In development | | | | |
| United Tech | United Technologies | | | | | | | | | |
| | 40,000 | 178 | 300 | нтрв | IRFNA | Flown on Firebolt air- launched target drone, 1968 | | | | |
| StarsTruck | | | | | | | | | | |
| | 40,000 | 178 | | CTBN | LOx | Flown on Dolphin water- launched sounding rocket, 1984 | | | | |
| USAF Acad | lemy | | | | | | | | | |
| H-1 | 55 | 0.25 | 2.3 | нтрв | GOx | Flown on 4-ft tall rocket for student project, 1991 | | | | |

Figure: American Rocket Company = SpaceDev

M. Peet Lecture 11: Spacecraft Dynamics 19 / 31

| *** | Throat Throat | Average Thrust (MI) | Burn Bunstion BHC | Feet | Oxidae | Comments |
|------------|------------------|---------------------------|-------------------------|------|--------|--|
| American I | Incist Corps | ry . | | | | |
| 14-900 | 75,888 | 300 | 74 | MTP6 | LOw | Quelted to triple |
| +450 | 30,888 | 140 | | RIPE | 60x | avainable. |
| 6-50 | 16,600 | 44 | | PIPE | 50x | ti-divelopment |
| 6-59 | 8,300 | 19 | | HIPE | 90x | th-day-elopment |
| 81 | 100 | 3,44 | | HTFU | 10x | ti-development |
| Delet 11c | notoper | | | | | |
| | 40,000 | CM | 300 | 1699 | SECOLA | Flours on Finded air bunched larget drawn 1968 |
| Zerc'out | _ | - | | _ | | |
| | *0000 | CS. | | стви | LON | Flows on Dogities was burnshed sounding rocket, 1964 |
| SM AN | denty | | | | | |
| 8-1 | 55 | 095 | 2.3 | HTFE | SCX | Flows or A-fried red for purpose project, I |

- HTPB is a common plastic/rubber hybrid. Also used occasionally in solid rockets
- Commercial sources include paraffin and spandex.

Electric Propulsion

Electrothermal:

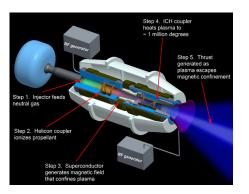
Ohmic Heating

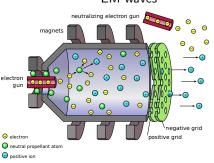
Electrostatic:

Repulsion/Attraction

Electromagnetic:

 Ions accelerated by EM waves





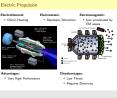
Advantages:

Very High Performance

Disadvantages:

- Low Thrust
- Requires Electricity

-Electric Propulsion



On left is a magnetoplasmadynamic thruster (MPD)

- Requires MW power for radio heating and magnetic confinement
- Requires a nuclear reactor for power.
- Only experimental MPDs have flown to date.

On right is a gridded ion thruster

- The US in the 1960s focused on GITs, while the Soviet union focused on Hall Effect Thrusters (HET)
- Common for stationkeeping (in GEO)
- Isp in the range 3k-10k (maybe 21k)

Electric Propulsion

The choice of Electrothermal/Electrostatic/Electromagnetic depends on available power.

| Electrothermal | Electrostatic | Electromagnetic |
|--|---|---|
| Gas heated via resistance element or arc and expanded through nozzle Resistojets Arcjets | Ions electrostatically accelerated Hall effect (HET) Ion Field emission | Plasma accelerated via interaction of current and magnetic field Pulsed plasma (PPTs) Magnetoplasmadynamic (MPD) Pulsed inductive (PIT) |
| Power Range; 0.4-2 kW | 1–50 kW | 50 kW-1 MW |
| Specific Impulse, I _{sp} ; 300–800 sec | 1,000–3,000 sec | 2,000–5,000 sec |

-Electric Propulsion

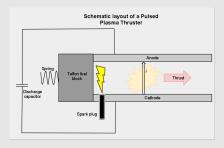
The choice of Electrothermal/Electrostatic/Electromagnetic depends or

Electric Propulsion

| Decrebental | Dectrostatic | Beckenapsele | | |
|--|---|--|--|--|
| Gas heated via testifance element or art and expanded through scottle standarders Argets | loss electrostatically accelerated Hall effect (HET) los Field entission | Plasma accelerated via interaction of current and magnetic field Prised plasma (PPTs) Magnetoplasmadynamic (MPC) Pulsed inductive (PIT) | | |
| Power Filinger 0.4-2 kW | 1-50 KW | 50 kW-1 MW | | |
| Specific Impulse, (_{ac} : 500-600 pec | 1,000-3,000 sec | 2,000-5,000 see | | |

SRP average generation is 3.2MW.

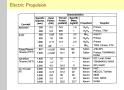
PPT's have flown since 1964. In 2000, NASA's research PPT generated c=13,700 m/s (Isp=1,370), with thrust of 860 micro-N, requiring power of 70 W.



Electric Propulsion

| | | | C | haracteris | tics | |
|----------------|-------------------------------|-------------------------|------------------------------|------------------------------|-------------------------------|----------------------------|
| Concept | Specific Impulse, (sec) | Input Power, (kW) | Thrust/ Power, (mN/kW) | Specific Mass, (kg/kW) | Propellant | Supplier |
| Resistojet | 296 | 0.5 | 743 | 1.6 | N ₂ H ₄ | Primex |
| | 299 | 0.9 | 905 | 1 . | N ₂ H ₄ | Primex, TRW |
| Arcjet | 480 | 0.85 | 135 | 3.5 | NH ₃ | IRS/ITT |
| | 502 | 1.8 | 138 | 3.1 | N ₂ H ₄ | Primex |
| | >580 | 2.17 | 113 | 2.5 | N ₂ H ₄ | Primex |
| | 800 | 26* | _ | _ | NH ₃ | TRW, Primex, CTA |
| Pulsed Plasma | 847 | < 0.03† | 20.8 | 195 | Teflon | JHU/APL |
| Thruster (PPT) | 1,200 | < 0.02† | 16.1 | 85 | Teflon | Primex, TSNIIMASH, NASA |
| Hall Effect | 1,600 | 1.5 | 55 | 7 | Xenon | IST, Loral, Fakel |
| Thruster (HET) | 1,638 | 1.4* | | | Xenon | TSNIIMASH, NASA |
| · | 2,042 | 4.5 | 54.3 | 6 | Xenon | SPI, KeRC |
| Ion Thruster | 2,585 | 0.5 | 35.6 | 23.6 | Xenon | HAC |
| (IT) | 2,906 | 0.74 | 37.3 | 22 | Xenon | MELCO, Toshiba |
| | 3,250 | 0.6 | 30 | 25 | Xenon | MMS |
| | 3,280 | 2.5 | 41 | 9.1 | Xenon | HAC, NASA |
| | 3,400 | 0.6 | 25.6 | 23.7 | Xenon | DASA |

M. Peet Lecture 11: Spacecraft Dynamics 22 / 31



Teflon melts at 327° C (260° C for cooking). Boils at 400° C

Staging

Previously, we assumed the rocket only consisted of payload and propellant: $m_0=m_L+m_p.$

$$\frac{m_p}{m_0} = 1 - e^{-\frac{\Delta v}{c}} \qquad \Delta v = c \ln \left[\frac{m(t_0)}{m(t_f)} \right] = c \ln \left[\frac{m_L + m_p}{m_L} \right]$$

Which would mean the only way to increase Δv is to decrease payload or increase the size of the rocket.

However: Payload is not the only part of the rocket.

- Rocket engines and storage tanks are heavy.
- Typically, structure accounts for $\cong 1/7$ of the propellant weight

$$m_0 = m_L + m_s + m_p = (m_L + 1/7m_p) + m_p$$

• While 1/7 may not seem a lot, without staging, it limits the total Δv to

$$\Delta v = c \ln \left(\frac{m_p}{m_p/7} \right) = c \ln 7 \cong 2c \cong 6km/s$$
 (assuming $m_L = 0$)

But $\Delta v = 8 \text{km/s}$ is needed for low earth orbit (LEO) - not accounting for drag or gravity losses (2km/s)!

OMG: Space flight is IMPOSSIBLE!

It's a conspiracy.

M. Peet Lecture 11: Spacecraft Dynamics 23 / 31



Staging Provisorly, we assumed the rocket only consisted of payload and propellant:
$$\begin{split} &m_0 = m_L + m_V \\ &m_0 = m_L + m_V \end{aligned} \frac{m_e}{m_e} = 1 - e^{-\frac{\Delta k}{2}} \quad \Delta v = \text{ch}\left[\frac{m(e_0)}{m(L)}\right] = \text{ch}\left[\frac{m_L + m_V}{m_L}\right] \end{split}$$

Which would mean the only way to increase Δv is to decrease payload or increase the size of the rocket.

However: Payload is not the only part of the rocket.

Rocket engines and storage tanks are heavy.
 Typically, structure accounts for @ 1/7 of the propellant weight.

$$\begin{split} m_0 = m_L + m_r + m_p = (m_L + 1/7m_p) + m_p \\ & \text{While } 1/7 \text{ may not seen a lock without staging, it limits the total <math>\Delta v$$
 to $\Delta v = m_L \frac{m_{em}^2}{m_e} = \ln^2 n \cdot \frac{n_e}{2} \times v \cdot \ln n_e \cdot m_{em} m_e = 0) \\ \text{Bit } \Delta v = \frac{n_e}{n_e} \frac{m_{em}^2}{m_e n_e} = 0 \cdot \ln n_e \cdot \frac{n_e}{n_e} \cdot \ln n_e \cdot m_e \cdot m$

This is why Hohmann was so excited about relatively small changes in \boldsymbol{c}

$$\Delta v_{\rm max} = c \ln 7 \cong 2c \cong 6km/s$$
 (assuming $m_L = 0$)

Structural Mass on Saturn V

Structural Mass on Saturn V

[From ESA] - Cameras mounted on the Soyuz Fregat upper stage that sent Sentinel-1A into space on 3 April 2014. It shows liftoff, the stages in the rocket's ascent and the Sentinel-1A satellite being released from the Fregat upper stage to start its life in orbit around Earth.

The 2.3 tonne satellite lifted off on a Soyuz rocket from Europe's Spaceport in Kourou, French Guiana at 21:02 GMT (23:02 CEST). The first stage separated 118 sec later, followed by the fairing (209 sec), stage 2 (287 sec) and the upper assembly (526 sec). After a 617 sec burn, the Fregat upper stage delivered Sentinel into a Sun-synchronous orbit at 693 km altitude. The satellite separated from the upper stage 23 min 24 sec after liftoff.

M. Peet Lecture 11: Spacecraft Dynamics

25 / 31

Structural Coefficient

Definition 2.

The ratio of structure to total mass is called the **structural coefficient**, ϵ :

$$\epsilon = \frac{m_s}{m_s + m_p}$$

In the ideal case, structural weight would be discarded as soon as it is no longer required.

Continuous Staging

In this ideal scenario, we would have

$$\Delta v = (1 - \epsilon)c \ln \left[\frac{m_0}{m_L} \right]$$

- The structure simply decreases the efficiency of the fuel!
 In Staging, we discard structure at discrete points in time.
 - Staging can never be better than $\Delta v = (1-\epsilon)c\ln\left[\frac{m_0}{m_L}\right]$.

M. Peet Lecture 11: Spacecraft Dynamics

Definition 2. The ratio of electrons to both mass is called the attractional condition $\frac{1}{2} = \frac{m_{eff}}{m_{eff}} = \frac{m_{eff}}{$

Structural Coefficient

- ullet Prussing uses structural coefficient ϵ
- Prussing uses the term "mass ratio" to refer to the full weight of a stage over the empty weight (wet weight over dry weight).

$$Z = \frac{m_p + m_s + m_L}{m_s + m_L} = \frac{1 + \lambda}{\epsilon + \lambda}$$

 Prussing uses the term "payload ratio" to indicate the ratio of payload to structural mass plus propellant mass.

$$\lambda = \frac{m_L}{m_p + m_s}$$

 I use the term "structural mass fraction" to indicate the mass of structure needed for every mass of fuel

$$\eta := \frac{m_s}{m_p} = \frac{\epsilon}{1 - \epsilon}$$

Δv for staging

Total Δv is the sum of the Δv 's from each stage:

$$\Delta v = \Delta v_1 + \Delta v_2 + \Delta v_3$$

So the Δv of each stage is

$$\Delta v_i = c \ln \frac{m_{0,i}}{m_{f,i}} = c \ln \frac{m_{0,i}}{m_{L,i} + m_{s,i}} = c \ln Z_i = c \ln \left(\frac{1 + \lambda_i}{\lambda_i + \epsilon_i}\right)$$

The total mass of each state is the payload, propellant and structural mass

$$m_{0,i} = m_{p,i} + m_{s,i} + m_{L,i}$$

The payload mass for each stage is the total mass of the following stages

$$m_{L,i} = m_{0,i+1} = m_{p,i+1} + m_{s,i+1} + m_{L,i+1}$$

When designing a multi-stage rocket: the only thing you are allowed to choose is $m_{p,i}$. These are the variables. Everything else is fixed by these choices.

$$m_{s,i} = \frac{\epsilon_i}{1 - \epsilon_i} m_{p,i} = \eta_i m_{p,i}$$

M. Peet

3-stage Scenario

Suppose we divide the structural and propulsive weight into three components

1. First Stage: m_{s1} , m_{p1}

2. Second Stage: m_{s2} , m_{p2}

3. Third Stage: m_L , m_{p3}

Then Δv is the combined Δv of all three stages.

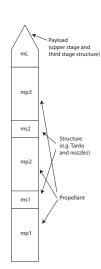
$$\begin{split} \Delta v_T &= \Delta v_1 + \Delta v_2 + \Delta v_3 (m_L \text{ here includes } m_{s3}) \\ &= c \ln \left[\frac{m_{p1} + m_{p2} + m_{p3} + m_{s1} + m_{s2} + m_L}{m_{p2} + m_{p3} + m_{s1} + m_{s2} + m_L} \right] \\ &+ c \ln \left[\frac{m_{p2} + m_{p3} + m_{s2} + m_L}{m_{p3} + m_{s2} + m_L} \right] + c \ln \left[\frac{m_{p3} + m_L}{m_L} \right] \end{split}$$

Optimal choice of m_{p1} , m_{p2} and m_{p3} is difficult.

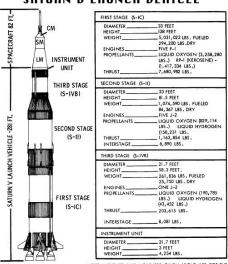
For a fixed total mass, m_0 , we can maximize

- Payload weight
- Total Δv

A good rule of thumb is $m_{p1} = 3m_{p2} = 9m_{p3}$.



SATURN U LAUNCH VEHICLE



NOTE: WEIGHTS AND MEASURES GIVEN ABOVE ARE FOR THE NOMINAL VEHICLE CONFIGURATION FOR APOLLO 10. THE FIGURES MAY VARY SLIGHTLY DUE TO CHANGES BEFORE LAUNCH TO MEET CHANGING CONDITIONS.

3-stage Scenario

Suppose we divide the structural and propulsive weight into three components 1. First Stage: max. max

2. Second Stage: may may 3. Third Stage: mr. may

Then Δv is the combined Δv of all three stares $\Delta v_T = \Delta v_1 + \Delta v_2 + \Delta v_3 (m_L \text{ here includes } m_{s3})$

For a fixed total mass, mg, we can maximize

· Payload weight Total Av A good rule of thumb is $m_{a1} = 3m_{a2} = 9m_{a3}$

Structural coefficient by stage (assuming interstage is structural mass on previous stage:)

 $\epsilon_1 = .0602$

 $\epsilon_2 = .0868$

 $\epsilon_3 = .0985$

figure from National Air and Space Museum

Comparison: Ariane IV (1988):

 $\epsilon_1 = .0696$

 $\epsilon_2 = .0957$

 $\epsilon_3 = .01008$

mass=500,000-1,000,000lbComparison: BFR

(Starship+Superheavy)

 $\epsilon_1 = .0651$ (est.)

 $\epsilon_2 = .0909$

mass=11,000,000lb



1,2 and 3stage Scenarios (Fixed Total Mass)

TABLE 6.3 ONE-, TWO-, AND THREE-STAGE ROCKETS STAGES (EQUAL ϵ AND λ) c=3048 m/sec ($I_{SP}=311$ sec)

| | 1 stage | 2 stage | 3 stage | |
|-------------------|----------|---------|-----------------|----------------------|
| | | | specified m_L | specified Δv |
| m ₀₁ | 15,000 | 15,000 | 15,000 | 15,000 |
| m ₀₂ | - | 3,873 | 6,082 | 4,926 |
| m ₀₃ | | | 2,466 | 1,618 |
| m_{s1} | 2,000 | 1,590 | 1,274 | 1,393 |
| m_{s2} | <u>-</u> | 410 | 517 | 457 |
| m_{s3} | _ | | 209 | 150 |
| m_{p1} | 12,000 | 9,537 | 7,644 | 8,681 |
| n_{p2} | <u>-</u> | 2,463 | 3,099 | 2,851 |
| m_{p3} | _ | _ | 1,257 | 936 |
| m_L | 1,000 | 1,000 | 1,000 | 531 |
| € | 0.143 | 0.143 | 0.143 | 0.138 |
| λ | 0.0714 | 0.348 | 0.682 | 0.489 |
| Δν (m/sec) | 4,906 | 6,157 | 6,515 | 7,905 |
| $m_{s_{TOT}}$ | 2,000 | 2,000 | 2,000 | 2,000 |
| m _{PTOT} | 12,000 | 12,000 | 12,000 | 12,469 |
| Z^{mp} тот | 5 | 2.75 | 2.039 | 2.374 |

M. Peet Lecture 11: Spacecraft Dynamics 29 / 31

Staging on Minuteman ICBM

Summary

This Lecture you have learned:

Introduction to Rocketry

- Mass Consumption
- Specific Impulse and Rocket Types
- Δv limitations
- Staging